Waves in Two and Three Dimensions

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Introduction

So far, we’ve looked at waves in one dimension, traveling along a string or sound waves going down a narrow tube. But waves in higher dimensions than one are very familiar—water waves on the surface of a pond, or sound waves moving out from a source in three dimensions.

It is pleasant to find that these waves in higher dimensions satisfy wave equations which are a very natural extension of the one we found for a string, and—very important—they also satisfy the Principle of Superposition, in other words, if waves meet, you just add the contribution from each wave. In the next two paragraphs, we go into more detail, but this Principle of Superposition is the crucial lesson.

The Wave Equation and Superposition in One Dimension

For waves on a string, we found Newton’s laws applied to one bit of string gave a differential wave equation,

$$\frac{\partial^2 y}{\partial x^2} = \frac{1}{\nu^2} \frac{\partial^2 y}{\partial t^2}$$

and it turned out that sound waves in a tube satisfied the same equation. Before going to higher dimensions, I just want to focus on one crucial feature of this wave equation: it’s linear, which just means that if you find two different solutions \( y_1(x,t) \) and \( y_2(x,t) \) then \( y_1(x,t) + y_2(x,t) \) is also a solution, as we proved earlier.

This important property is easy to interpret visually: if you can draw two wave solutions, then at each point on the string simply add the displacement \( y_1(x,t) \) of one wave to the other \( y_2(x,t) \)—you just add the waves together—this also is a solution. So, for example, as two traveling waves moving along the string in opposite directions meet each other, the displacement of the string at any point at any instant is just the sum of the displacements it would have had from the two waves singly. This simple addition of the displacements is termed “interference”, doubtless because if the waves meeting have displacement in opposite directions, the string will be displaced less than by a single wave. It’s also called the Principle of Superposition.

The Wave Equation and Superposition in More Dimensions

What happens in higher dimensions? Let’s consider two dimensions, for example waves in an elastic sheet like a drumhead. If the rest position for the elastic sheet is the \((x,y)\) plane, so when it’s vibrating it’s moving up and down in the \(z\)-direction, its configuration at any instant of time is a function \( z(x,y,t) \).
In fact, we could do the same thing we did for the string, looking at the total forces on a little bit and applying Newton’s Second Law. In this case that would mean taking one little bit of the drumhead, and instead of a small stretch of string with tension pulling the two ends, we would have a small square of the elastic sheet, with tension pulling all around the edge. Remember that the net force on the bit of string came about because the string was curving around, so the tensions at the opposite ends tugged in slightly different directions, and didn’t cancel. The \( \frac{\partial^2 y}{\partial x^2} \) term measured that curvature, the rate of change of slope. In two dimensions, thinking of a small square of the elastic sheet, things are more complicated. Visualize the bit of sheet to be momentarily like a tiny patch on a balloon, you’ll see it curves in two directions, and tension forces must be tugging all around the edges. The total force on the little square comes about because the tension forces on opposite sides are out of line if the surface is curving around, now we have to add two sets of almost-opposite forces from the two pairs of sides. I’m not going to go through all the math here, but I hope it’s at least plausible that the equation is:

\[
\frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial y^2} = \frac{1}{v^2} \frac{\partial^2 z}{\partial t^2}.
\]

The physics of this equation is that the acceleration of a tiny bit of the sheet comes from out-of-balance tensions caused by the sheet curving around in both the x- and y-directions, this is why there are the two terms on the left hand side.

Remarkably, this same equation comes out for water waves (at least for small amplitudes), sound waves, and even the electromagnetic waves we now know as radio, microwaves, light, X-rays: so it’s called the Wave Equation.

And, going to three dimensions is easy: add one more term to give

\[
\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2}.
\]

This sum of partial differentiations is so common in physics that there’s a shorthand:

\[
\nabla^2 f = \left(1/v^2\right) \frac{\partial^2 f}{\partial t^2}.
\]

Just as we found in one dimension traveling harmonic waves \( f(x-\nu t) = A \sin(\omega t + \omega t) \), with \( \omega = \nu k \), you can verify that the three-dimensional equation has harmonic solutions

\[
f(x,y,z,t) = A \sin(k_x x + k_y y + k_z z - \omega t)
\]

and now

\[
\omega = \nu |k|, \text{ where } |k| = \sqrt{k_x^2 + k_y^2 + k_z^2}.
\]
In fact, $\vec{k}$ is a vector in the direction the wave is moving. The electric and magnetic fields in a radio wave or light wave have just this form (or, closer to the source, a very similar equivalent expression for outgoing spheres of waves, rather than plane waves).

It’s important to realize that this more complicated equation is still a *linear* equation—*the principle of superposition still holds*. If two waves on an elastic sheet, or the surface of a pond, meet each other, the result at any point is given by simply adding the displacements from the individual waves. (Assuming as always small waves, so the water waves don’t fall apart into foam.)

We’ll begin by thinking about waves propagating freely in two and three dimensions, than later consider waves in restricted areas, such as a drum head.

**How Does a Wave Propagate in Two and Three Dimensions?**

A one-dimensional wave doesn’t have a choice: it just moves along the line (well, it could get partly reflected by some change in the line and part of it go backwards). But when we go to higher dimensions, how a wave disturbance starting in some localized region spreads out is far from obvious. But we can begin by recalling some simple cases: dropping a pebble into still water causes an outward moving circle of ripples. If we grant that light is a wave, we notice a beam of light changes direction on going from air into glass. Of course, it’s not immediately evident that light *is* a wave: we’ll talk a lot more about that later.

**Huygen’s Picture of Wave Propagation**

If a point source of light is switched on, the wavefront is an expanding sphere centered at the source. Huygens suggested that this could be understood if at any instant in time each point on the wavefront was regarded as a source of secondary wavelets, and the new wavefront a moment later was to be regarded as built up from the sum of these wavelets. For a light shining continuously, this process just keeps repeating.
Huygens’ picture of how a spherical wave propagates: each point on the wave front is a source of secondary wavelets that generate the new wave front.

What use is this idea? For one thing, it explains refraction—the change in direction of a wavefront on entering a different medium, such as a ray of light going from air into glass.

If the light moves more slowly in the glass, velocity $v$ instead of $c$, with $v < c$, then Huygen’s picture explains Snell’s Law, that the ratio of the sines of the angles to the normal of incident and transmitted beams is constant, and in fact is the ratio $c/v$.

Snell’s Law: a ray of light entering glass from air is bent towards the normal, and $\sin \theta_1 / \sin \theta_2$ is the same for any entering angle.
This is evident from the diagram below: in the time the wavelet centered at \( A \) has propagated to \( C \), that from \( B \) has reached \( D \), the ratio of lengths \( AC/BD \) being \( c/v \). But the angles in Snell’s Law are in fact the angles \( ABC, BCD \), and those right-angled triangles have a common hypotenuse \( BC \), from which the Law follows.

**Huygens’ explanation of refraction:** showing two wavelets from the wavefront \( AB \):

\( W_B \) is slowed down compared with \( W_A \), since it is propagating in glass. This turns the wave front through an angle.

Huygens’ picture also provides a ready explanation of what happens when a plane wave front encounters a barrier with one narrow opening: and by narrow, we mean small compared with the wavelength of the wave. It’s easy to arrange this for water waves: it’s found that on the other side of the barrier, the waves spread out in circular fashion from the small hole.
A plane wave encounters a barrier with an opening smaller than a wavelength: the wave spreads in circular fashion on the far side.

Two-Slit Interference: How Young measured the Wavelength of Light

If the slit is wider than a wavelength or so, the pattern gets more complicated, as we would expect from Huygens’ ideas, because now the waves on the far side arise from a line of sources, not what amounts to one point. To investigate this further, consider the simplest possible next case: a barrier with two small holes in it, so on the far side we’re looking at waves radiating outwards from, effectively, two point sources.

Waves spreading out from two small slits in a barrier: the blue circles represent wave crests, where two cross the wave has maximum positive value, for example along the central line.

For two synchronized sources generating harmonic waves, at any point in the tank equally distant from the two sources (the central line in the picture above), the waves will add, the water will be maximally disturbed. For light waves, there will be a maximum in brightness at the center of a screen as shown in the diagram:
For light waves passing through two narrow slits and shining on a screen (on the right) there will be another bright spot at a point \( P \) away from the center \( C_2 \) of the screen, provided the distances of \( P \) from the two slits differ by a whole number of wavelengths:

\[ S_2Q = \lambda \]

Waves passing through two narrow slits in a barrier. If the distance \( S_2P \) to point \( P \) on the screen is exactly one wavelength longer than \( S_1P \), the waves will arrive at \( P \) in phase and reinforce each other.
On the other hand, at a point approximately half way from the center of the screen to $P$ the waves from the two sources will arrive at the screen exactly out of phase: the crest of one will arrive with the trough of the other, they will cancel, and there will be no light. Evidently, then, we will see on the screen a series of bright areas and dark areas, the brightest spots being at the points where the waves from the two slits arrive exactly in phase.

There is a Flash animation of this pattern formation here.

This pattern, generated by what is called interference between the waves, and also referred to as a diffraction pattern is historically important, because it was used to establish that light is a wave, by Thomas Young in 1807. (Recall Newton had believed light was a stream of particles, and that was very widely accepted at the time.)

Young used the pattern to find the wavelengths of red and violet light. His method can be understood from the diagram above. We did the experiment in class with a slit separation of about 0.2 mm., giving bright spots on the screen about 3 cm apart, with a screen 10 m from the slits.

That is to say, in the diagram above we had $S_1S_2 = 0.2 \times 10^{-3}\text{ m}$, $C_1C_2 = 9.5\text{ m}$, and we found $C_2P = x = 3\text{ cm}$. (within a percent or two). Looking at the diagram, it’s clear that the angle to $P$ from the slits is very small, in fact it’s $x/L = 3.15 \times 10^{-3}\text{ radians}$. So the diagram as drawn is very exaggerated!

Now, the line $S_1Q$ is perpendicular to the light rays setting off for $P$ (they are extremely close to parallel). The angle between $S_1Q$ and $S_1S_2$ is the same as that between $C_1P$ and $C_1C_2$, that is, $3.15 \times 10^{-3}\text{ radians}$. This means that the lengths $S_1Q$ and $S_1S_2$ are effectively equal, and therefore that

$$\frac{S_2Q}{S_1S_2} = \frac{\lambda}{d} = \frac{x}{L} = 3.15 \times 10^{-3}.$$

This is very accurate for such a small angle, and for the data as given here the wavelength of the light $\lambda = 3.15 \times 10^{-7}\text{ m} = 6.3 \times 10^{-7}\text{ m} = 630\text{ nm}$.

**Another Bright Spot**

About ten years after Young’s result a French civil engineer, Augustin Fresnel, independently developed a wave theory of light, and gave a more complete mathematical analysis. This was disputed by the famous French mathematician Simeon Poisson, who pointed out that if the wave theory were true, one could prove mathematically that in the sharp shadow of a small round object, there would be a bright spot in the center, because the waves coming around the circumference all around would add there. This seemed ridiculous—but French physicist Francois Arago actually did the experiment, and found the spot! The wave theory of light had arrived.