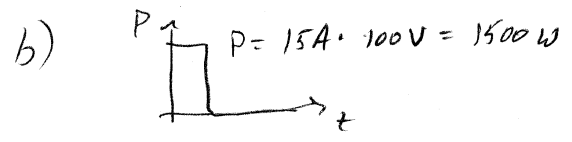
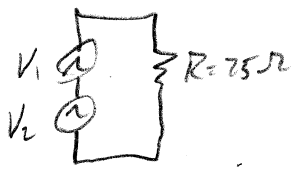


a) $I_{rms} = \sqrt{(15A)^2 \cdot \frac{0.1}{1.0}} = 4.7 A$



$P_{ave} = 1500 \cdot \frac{0.1}{1.0} = \underline{150 W}$

44.



$V_1 = 5.0V \cos(\omega t - \alpha)$
 $V_2 = 5.0V \cos(\omega t + \alpha) \rightarrow V_0$
 $\alpha = \pi/6$

a) $I = \frac{V_1 + V_2}{R} = \frac{V_0}{R} [\cos(\omega t - \alpha) + \cos(\omega t + \alpha)]$
 $= \frac{V_0}{R} \cdot 2 \cos\left(\frac{(\omega t - \alpha) + (\omega t + \alpha)}{2}\right) \cos\left(\frac{(\omega t - \alpha) - (\omega t + \alpha)}{2}\right)$
 $= \frac{2V_0}{R} \cos \alpha \cos \omega t$

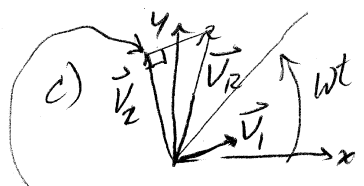
$\approx 0.35 A \cdot \cos \omega t$

b) $\vec{V}_1 + \vec{V}_2 = \vec{V}_R = \text{Voltage drop across } R$

$|\vec{V}_1| = V_0$
 $\frac{|\vec{V}_R|}{2} = V_0 \cos \alpha$

$|\vec{V}_R| = IR = 2V_0 \cos \alpha \Rightarrow I = \frac{2V_0}{R} \cos \alpha$

look at $\vec{V}_R \Rightarrow$ phase is clearly ωt



right angle
 $\cos^2 \alpha = \frac{\pi}{4}$

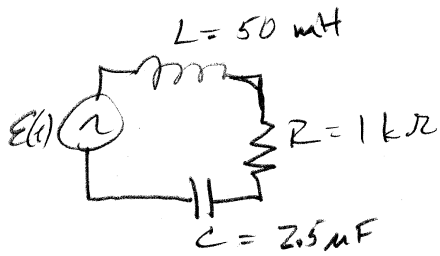
$|\vec{V}_R| = \sqrt{|\vec{V}_1|^2 + |\vec{V}_2|^2}$

$= \sqrt{5^2 + 5^2} = 7.1 V \Rightarrow I = \frac{|\vec{V}_R|}{R} = 0.34 A$

angle between \vec{V}_R & $\vec{V}_2 = \cos^{-1} \frac{|\vec{V}_2|}{|\vec{V}_R|} = 35.5^\circ = 0.62 \text{ rad} = \theta$

$\Rightarrow I = 0.34 A \cdot \cos(\omega t + 0.65 \text{ rad})$

54-



$$a) f_{\text{resonance}} = \frac{1}{2\pi} \cdot \frac{1}{\sqrt{LC}}$$

$$= 450 \text{ Hz}$$

$$b) Q = \frac{\omega_0 L}{R} = \frac{2\pi \cdot 450 \cdot 50 \text{ mH}}{1 \text{ k}\Omega} = 0.14$$

c) $Q = \frac{\omega_0}{\Delta\omega} = \frac{f_0}{\Delta f}$ is wrong here because Q is too small

$$\text{So, } P_{\text{av}} = \frac{\frac{1}{2} \epsilon_0^2 R \omega^2}{L^2 (\omega^2 - \omega_0^2)^2 + \omega^2 R^2}$$

$$\text{Max. average Power} = \frac{\frac{1}{2} \epsilon_0^2 R \omega^2}{\omega^2 R^2} = \frac{1}{2} \frac{\epsilon_0^2}{R}$$

$$\text{So find } \frac{P_{\text{av}}}{P_{\text{av max}}} = \frac{1}{2} = \frac{\omega^2 R^2}{L^2 (\omega^2 - \omega_0^2)^2 + \omega^2 R^2}$$

$$L^2 (\omega^2 - \omega_0^2)^2 + \omega^2 R^2 = 2\omega^2 R^2$$

$$\frac{R}{2L} = 10^4$$

$$\omega_0^2 = 8 \times 10^6$$

$$L(\omega^2 - \omega_0^2) = \pm \omega R$$

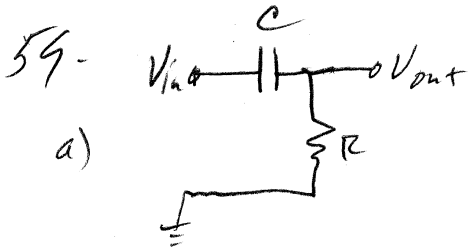
$$\omega^2 \mp \frac{R}{L} \omega - \omega_0^2 = 0 \Rightarrow \omega = \frac{\pm R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 + \omega_0^2}$$

$$= \pm 10^4 \pm \sqrt{10^8 + 8 \times 10^6}$$

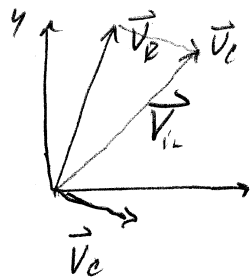
$$= \pm 10^4 \pm 10,392$$

$$= \begin{matrix} 392 \\ 20,392 \\ -392 \\ -20,392 \end{matrix} \left. \begin{matrix} \text{rad/s} \\ \text{Answers} \end{matrix} \right\} \Rightarrow f = \begin{cases} 62 \text{ Hz} \\ 3,250 \text{ Hz} \end{cases}$$

negative (beg > 0)



$$V_{in} = V_0 \cos \omega t$$



$$\vec{V}_{in} = \vec{V}_C + \vec{V}_R$$

$$\vec{V}_{out} = \vec{V}_R$$

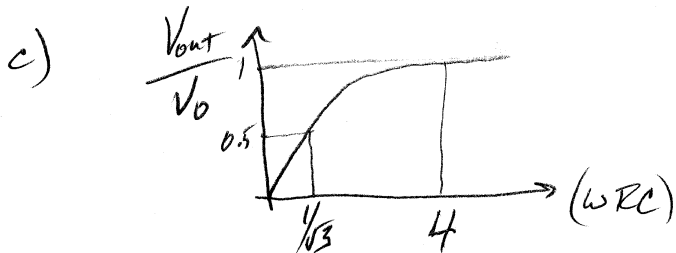
$$V_{out} = IR$$

$$V_{in} = I \cdot Z_T \quad Z_T = \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}$$

$$|\vec{V}_{out}| = V_{out} = IR = \frac{V_{in}}{Z_T} \cdot R = \frac{V_0 R}{\sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}} = \frac{V_0}{\sqrt{1 + \left(\frac{1}{\omega RC}\right)^2}}$$

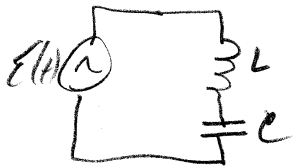
b)

$$V_{out} = \frac{V_0}{2} \Rightarrow 1 + \left(\frac{1}{\omega RC}\right)^2 = 4 \Rightarrow (\omega RC)^2 = \frac{1}{3} \Rightarrow \omega = \frac{1}{RC\sqrt{3}}$$



$$\frac{V_{out}}{V_0} = \frac{1}{\sqrt{1 + \left(\frac{1}{\omega RC}\right)^2}}$$

70-



$$a) \quad \mathcal{E}(t) = \mathcal{E}_0 \cos \omega t = L \frac{dI}{dt} + \frac{Q}{C} \quad \text{say } I = \frac{dQ}{dt}$$

$$= L \frac{d^2Q}{dt^2} + \frac{Q}{C}$$

b) $Q = Q_0 \cos \omega t$ a solution? check

$$\frac{d^2Q}{dt^2} = -\omega^2 Q_0 \cos \omega t \Rightarrow L(-\omega^2 Q_0) + \frac{Q_0}{C} = \mathcal{E}_0$$

$$\Rightarrow Q_0 = \frac{\mathcal{E}_0}{\frac{1}{C} - \omega^2 L} = \frac{\mathcal{E}_0}{L(\frac{1}{LC} - \omega^2)}$$

$$= \frac{\mathcal{E}_0}{L(\omega_0^2 - \omega^2)} = -\frac{\mathcal{E}_0}{L(\omega^2 - \omega_0^2)}$$

(whatever)

$$c) \quad I = \frac{dQ}{dt} = -\omega Q_0 \sin \omega t$$

$$= -\omega Q_0 \cos(\omega t - \frac{\pi}{2})$$

$$= \frac{\omega \mathcal{E}_0}{L(\omega^2 - \omega_0^2)} \cos(\omega t - \frac{\pi}{2})$$

Want $I_0 > 0$

when $\omega > \omega_0$, $\frac{\omega \mathcal{E}_0}{L(\omega^2 - \omega_0^2)} = I_0$ phase is $(\omega t - \frac{\pi}{2})$

$\omega < \omega_0$, $\frac{\omega \mathcal{E}_0}{L(\omega^2 - \omega_0^2)} = -I_0$, phase is $(\omega t + \frac{\pi}{2})$

so $I = I_0 \cos(\omega t - \delta)$ where $I_0 = \frac{\omega \mathcal{E}_0}{L|\omega^2 - \omega_0^2|} = \frac{\mathcal{E}_0}{|X_L - X_C|}$

but $\delta = \begin{cases} \frac{\pi}{2} & \text{for } \omega > \omega_0 \\ -\frac{\pi}{2} & \text{for } \omega < \omega_0 \end{cases}$