

Supplement 3 - Evaluating $\langle S_z \rangle$

In class, I claimed that we could express

$$\langle j m_j | S_z | j m_j \rangle \text{ as } \langle j m_j | \frac{\frac{S_z}{j^2} J_z}{j(j+1)} | j m_j \rangle$$

$$= \delta_{m_j} \cdot \frac{1}{2} \frac{j(j+1) - l(l+1) - \frac{3}{4}}{j(j+1)}$$

I will prove that here using angular momentum algebra.

To really evaluate $\langle S_z \rangle$, need to express $| j m_j \rangle$ in L, S basis:

$$| j m_j \rangle = \alpha | m_l = m_j - \frac{1}{2}, m_s = \frac{1}{2} \rangle + \beta | m_l = m_j + \frac{1}{2}, m_s = -\frac{1}{2} \rangle$$

where I have already included the fact that $m_j = m_l + m_s$ (since $J_z = L_z + S_z$)

If we knew α and β , we'd have

$$\langle S_z \rangle = \frac{1}{2} |\alpha|^2 - \frac{1}{2} |\beta|^2 = \frac{1}{2} (|\alpha|^2 - |\beta|^2)$$

So we need to know α and β . That's the tricky part.

The most straightforward way to get them is to find the eigenstates of J^2 in the (m_l, m_s) basis.

Define $|1\rangle = |m_x = m, m_s = +\frac{1}{2}\rangle$
 $|2\rangle = |m_x = m+1, m_s = -\frac{1}{2}\rangle$
So $m_j = m + \frac{1}{2}$

We know $J^2 = (\vec{L} + \vec{S})^2 = L^2 + S^2 + 2\vec{L} \cdot \vec{S}$
 $= L^2 + S^2 + 2(L_x S_x + L_y S_y + L_z S_z)$

Recall from Chapter 4 the definitions [Eq. 4.105]

$$L_{\pm} = L_x \pm i L_y$$

$$S_{\pm} = S_x \pm i S_y$$

Using them, $\vec{L} \cdot \vec{S} = L_z S_z + \frac{1}{2}(L_+ S_- + L_- S_+)$

so $J^2 = L^2 + S^2 + 2L_z S_z + L_+ S_- + L_- S_+$

From Eq. 4.121, we know how L_{\pm}, S_{\pm} affect states.

So we get

$$\langle 1 | J^2 | 1 \rangle = \hbar^2 \left[l(l+1) + s(s+1) + 2m \cdot \frac{1}{2} \right]$$

$$= \hbar^2 \left[l(l+1) + \frac{3}{4} + m \right]$$

$$\langle 2 | J^2 | 2 \rangle = \hbar^2 \left[l(l+1) + \frac{3}{4} + 2(m+1)(-\frac{1}{2}) \right]$$

$$= \hbar^2 \left[l(l+1) + \frac{3}{4} - m - 1 \right]$$

$$\langle 1 | J^2 | 2 \rangle = \langle 1 | L_z S_z | 2 \rangle, \text{ since we need to increase } m_s \text{ and decrease } m_x$$

$$L_z |l, m\rangle = \underbrace{\hbar \sqrt{l(l+1) - (m+1)m}}_{(l, m)} |l, m\rangle$$

$$S_z | \frac{1}{2}, -\frac{1}{2} \rangle = \pm \sqrt{\frac{1}{2}(\frac{1}{2}+1) - (-\frac{1}{2})(-\frac{1}{2}+1)} | \frac{1}{2}, -\frac{1}{2} \rangle$$

$$= \pm \sqrt{\frac{3}{4} + \frac{1}{4}} | \frac{1}{2}, -\frac{1}{2} \rangle = \pm | \frac{1}{2}, -\frac{1}{2} \rangle$$

$$\text{So } \langle 1 | J^2 | 2 \rangle = \pm^2 \sqrt{l(l+1) - m(m+1)}$$

Since J^2 is hermitian, must have $\langle 2 | J^2 | 1 \rangle = (\langle 1 | J^2 | 2 \rangle)^*$
 $= \langle 1 | J^2 | 2 \rangle$

So we can make matrix representation of J^2 :

$$J^2 \rightarrow \pm^2 \left[l(l+1) + \frac{3}{4} \right] \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \pm^2 \begin{bmatrix} m & \sqrt{l(l+1) - m(m+1)} \\ \overline{\sqrt{l(l+1) - m(m+1)}} & -m-1 \end{bmatrix}$$

First part is diagonal in any basis, so
we need to diagonalize second part

$$\text{Solve } \begin{vmatrix} m-\lambda & Q \\ Q & -m-1-\lambda \end{vmatrix} = 0 \quad Q = \sqrt{l(l+1) - m(m+1)}$$

$$-(m-\lambda)(m+1+\lambda) - Q^2 = 0$$

$$-(m(m+1) - \lambda(m+1) + \lambda m - \lambda^2) - l(l+1) + m(m+1) = 0$$

$$\lambda^2 + \lambda - l(l+1) = 0$$

$$\lambda = \frac{1}{2} \left[-1 \pm \sqrt{1+4l(l+1)} \right]$$

$$= \frac{1}{2} \left[-1 \pm \sqrt{4l^2+4l+1} \right]$$

$$= \frac{1}{2} \left[-1 \pm (2l+1) \right]$$

$$\lambda_+ = l \quad \lambda_- = -l-1$$

So eigenvalues of J^2 are

$$\lambda_+ = \hbar^2 \left[l(l+1) + \frac{3}{4} \right] + \hbar^2 l$$

$$= \hbar^2 \left[l^2 + 2l + \frac{3}{4} \right]$$

$$= \hbar^2 (l + \frac{1}{2})(l + \frac{3}{2}) = \hbar^2 j(j+1) \quad \text{for } j = l + \frac{1}{2}$$

$$\text{and } \lambda_- = \hbar^2 \left[l(l+1) + \frac{3}{4} \right] - \hbar^2 (l+1)$$

$$= \hbar^2 \left[l^2 - \frac{1}{4} \right]$$

$$= \hbar^2 (l - \frac{1}{2})(l + \frac{1}{2}) = \hbar^2 j(j+1) \text{ for } j = l - \frac{1}{2}$$

These are the eigenvalues we expected, since
we get $j = l \pm \frac{1}{2}$ when we combine \vec{L} and $\vec{S} = \vec{i}$

But we want eigenstates.

First take $\lambda = \lambda_+$, so $j = l + \frac{1}{2}$

Need

$$\begin{bmatrix} m-l & Q \\ Q & -m-l-1 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = 0$$

$$\alpha(m-l) + \beta Q = 0$$

$$\alpha = -\beta \frac{Q}{m-l}$$

Need $|\alpha|^2 + |\beta|^2 = 1$

$$\text{so } |\beta|^2 \left[\frac{l(l+1) - m(m+1)}{(m-l)^2} + 1 \right] = 1$$

$$\text{Note } l(l+1) - m(m+1) = l^2 - m^2 + l - m \\ = (l-m)(l+m+1) = \alpha^2$$

So

$$|\beta|^2 \left[\frac{l+m+1}{l-m} + 1 \right] = 1$$

$$|\beta|^2 \left[\frac{2l+1}{l-m} \right] = 1$$

$$\beta = \sqrt{\frac{l-m}{2l+1}}$$

and

$$\alpha = \beta \frac{\sqrt{(l-m)(l+m+1)}}{l-m}$$

$$\alpha = \sqrt{\frac{l+m+1}{2l+1}}$$

So in this case, we get

$$\langle S_z \rangle = \frac{\hbar}{2} (|\alpha|^2 - |\beta|^2) \\ = \frac{\hbar}{2} \left[\frac{l+m+1 - (l-m)}{2l+1} \right] = \frac{\hbar}{2} \frac{2m+1}{2l+1}$$

$$\text{But recall } m_j = m + \frac{1}{2} \Rightarrow 2m+1 = 2m_j \\ j = l + \frac{1}{2} \Rightarrow 2l+1 = 2j$$

$$\boxed{\langle S_z \rangle = \frac{\hbar}{2} \frac{m_j}{j}} \quad (j = l + \frac{1}{2})$$

In comparison, we have

$$\langle S_z \rangle = \frac{\hbar}{2} \cdot m_j \cdot \frac{j(j+1) - l(l+1) + \frac{3}{4}}{j(j+1)}$$

$$\text{But here } l(l+1) = (j-\frac{1}{2})(j+\frac{1}{2}) = j^2 - \frac{1}{4}$$

So expression becomes

$$\langle S_z \rangle = \frac{\pm}{2} m_j \cdot \frac{j^2 + j - (j^2 - \frac{1}{4}) + \frac{3}{4}}{j(j+1)}$$
$$= \frac{\pm}{2} m_j \cdot \frac{j+1}{j(j+1)} = \frac{\pm}{2} \frac{m_j}{j}$$

and we see that two expression agree. ✓

Now we have to check the $j = l - \frac{1}{2}$ case, where $j = l - \frac{1}{2}$.

But we know eigenstates are orthogonal, so if

$$|j = l + \frac{1}{2}, m_j = m + \frac{1}{2}\rangle = \alpha |m_s = m, m_s = \frac{1}{2}\rangle + \beta |m_s = m+1, m_s = -\frac{1}{2}\rangle$$

then must have

$$|j = l - \frac{1}{2}, m_j\rangle = \beta |m_s = \frac{1}{2}\rangle - \alpha |m_s = -\frac{1}{2}\rangle$$

since that is the only orthogonal state

$$\text{So for this case, } \langle S_z \rangle = \frac{\pm}{2} (|\beta|^2 - |\alpha|^2)$$

$$= -\frac{\pm}{2} \frac{2m+1}{2l+1}$$

$$\text{Again, } 2m+1 = 2m_j$$

$$\text{But now } 2l+1 = 2(j + \frac{1}{2}) + 1 = 2j + 2 = 2(l + \frac{1}{2})$$

$$\boxed{\langle S_z \rangle = -\frac{\pm}{2} \frac{m_j}{j+1}} \quad (j = l - \frac{1}{2})$$

For comparison, if $\ell = j + \frac{1}{2}$ other expression is

$$\begin{aligned}\langle S_z \rangle &= \frac{\pm}{2} m_j \frac{j(j+1) - (j+\frac{1}{2})(j+\frac{3}{2}) + \frac{3}{4}}{j(j+1)} \\ &= \frac{\pm}{2} m_j \frac{j^2 + j - j^2 - 2j - \frac{3}{4} + \frac{3}{4}}{j(j+1)} \\ &= \frac{\pm}{2} m_j \frac{-j}{j(j+1)} = -\frac{\pm}{2} \frac{m_j}{j+1}\end{aligned}$$

Again, they agree. ✓

So the geometrical argument used in class
is indeed valid, even if the concepts
are a bit shaky.