

Gravitation and Cosmology

Lecture 2:

Lorentz-invariant quantities

As we saw last time, the Lorentz transformation for our special case is

$$\begin{pmatrix} t' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma(t - vx/c^2) \\ \gamma(x - vt) \\ y \\ z \end{pmatrix} \quad (2.1)$$

where $\gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$.

In general, the transformation from S to S' can be written as the product of a rotation and a *boost*. A boost is a transformation that applies to two systems with their axes aligned, moving with relative velocity \vec{v} . The general form of the transformation coefficients is

$$\Lambda^\mu{}_\nu = \begin{pmatrix} \gamma & -\gamma v^1/c & -\gamma v^2/c & -\gamma v^3/c \\ -\gamma v^1/c & 1 + (\gamma - 1) \hat{v}^1 \hat{v}^1 & (\gamma - 1) \hat{v}^1 \hat{v}^2 & (\gamma - 1) \hat{v}^1 \hat{v}^3 \\ -\gamma v^2/c & (\gamma - 1) \hat{v}^2 \hat{v}^1 & 1 + (\gamma - 1) \hat{v}^2 \hat{v}^2 & (\gamma - 1) \hat{v}^2 \hat{v}^3 \\ -\gamma v^3/c & (\gamma - 1) \hat{v}^3 \hat{v}^1 & (\gamma - 1) \hat{v}^3 \hat{v}^2 & 1 + (\gamma - 1) \hat{v}^3 \hat{v}^3 \end{pmatrix} \quad (2.2)$$

Now, it is easy to see that the inverse transformation to $\Lambda^\mu{}_\nu(\vec{v})$ is $\Lambda^\mu{}_\nu(-\vec{v})$. That is,

$$\sum_{\kappa=0}^3 \Lambda^\mu{}_\kappa(\vec{v}) \Lambda^\kappa{}_\nu(-\vec{v}) = \delta^\mu{}_\nu \quad (2.3)$$

(We will now drop the explicit \sum representing summations over repeated indices and use the Einstein summation convention that a repeated upper and lower index—like κ above—are summed from 0 to 3.)

Problem: Prove Eq. 2.3 by direct substitution of Eq. 2.2.

Now, by inspecting the special case Eq. 2.1 we see that the transformation closely resembles a rotation in a 4-dimensional space. One of the salient characteristics of a rotation is that it leaves lengths of vectors invariant. That is, ordinary 3-dimensional rotations do not affect the dot product

$$\vec{a} \cdot \vec{a} \equiv (a^1)^2 + (a^2)^2 + (a^3)^2.$$

Similarly, the Lorentz transformation does not affect the “dot product”

$$-s^2 = (x^0)^2 - (x^1)^2 - (x^2)^2 - (x^3)^2 \quad (2.4)$$

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That is,

$$-s'^2 = (x'^0)^2 - (x'^1)^2 - (x'^2)^2 - (x'^3)^2 = (x^0)^2 - (x^1)^2 - (x^2)^2 - (x^3)^2 = -s^2,$$

which the astute student will recognize as Eq. 1.11.

In a nutshell, if an observer in S measures the space-time coordinates \mathbf{x} of an event and an observer in S' measures the coordinates \mathbf{x}' of the same event, and if they calculate $-s^2$ and $-s'^2$, respectively, their results will be numerically the same.

The easiest way to see the invariance of $-s^2$ is by direct substitution. For simplicity, confine attention to the special case Eq. 2.1; then since $y' = y$ and $z' = z$, we have only to be sure

$$(ct')^2 - (x')^2 = (ct)^2 - (x)^2. \quad (1.11)$$

Of course this is correct because we used it to derive the Lorentz transformation in the first place!

Problem: demonstrate the invariance of $-s^2$ by direct substitution of the Lorentz transformation coefficients.

The coordinates \mathbf{x} of a space-time event are actually a difference between two coordinates.

Problem: Why is the preceding remark correct?

Thus we can generalize the Lorentz-invariance of $-s^2$ to an infinitesimal interval between space-time points \mathbf{x} and $\mathbf{x} + d\mathbf{x}$:

$$(d\mathbf{x})^2 = \frac{1}{c^2} \left[(dx^0)^2 - (dx^1)^2 - (dx^2)^2 - (dx^3)^2 \right] \equiv (dt)^2 - \vec{\mathbf{x}} \cdot \vec{\mathbf{x}} / c^2 \quad (2.5)$$

The infinitesimal Lorentz invariant quantity $d\mathbf{x}$ is called the *proper time*. Its physical significance can be understood as follows: suppose a rocket moves at velocity $\vec{\mathbf{u}}$ in the S system. We measure this velocity by measuring successive positions at successive ticks of a clock. Suppose the time-interval between ticks is dt . Then in time dt the rocket's position changes by $d\vec{\mathbf{x}} = \vec{\mathbf{u}} dt$. The proper time interval between successive position measurements is then

$$d\mathbf{x} = \left((dt)^2 - \vec{\mathbf{x}} \cdot \vec{\mathbf{x}} / c^2 \right)^{1/2} = dt \left(1 - \vec{\mathbf{u}} \cdot \vec{\mathbf{u}} / c^2 \right)^{1/2} \quad (2.6)$$

Now consider a system S' whose velocity $\vec{\mathbf{v}}$ relative to S just happens to be the value of $\vec{\mathbf{u}}$ at time t . Then as measured in S' the rocket has velocity 0 and the (Lorentz invariant) proper time interval has the value $d\mathbf{x}'$. In other words, the proper time is the time kept by the rocket pilot's own clock.

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Lecture 2:

Uniform acceleration in a fixed direction

Consider a rocket that---from the point of view of the passengers---has constant acceleration along the x -direction. That is, as measured in the rocket's own frame, in a time $d\tau$ (the time kept by the control-room clock) the rocket gains linear velocity

$$du = a d\tau . \quad (2.7)$$

What is the rocket's speed as seen from the frame S (*not* accelerating), with respect to which the rocket had speed 0 at $\tau=0$?

At time τ the rocket had speed v , and at time $\tau + d\tau$ it has speed $v + dv$, in the S system. To find the new speed we use the formula for addition of velocities: in a frame S' moving with velocity v in the x -direction, the rocket has (after time $d\tau$) speed $ad\tau$. (By taking $d\tau$ as small as we like, we can insure that the velocity du is extremely small compared with c .)

The speed in S is then

$$v + dv = \frac{v + du}{1 + vdu/c^2} \approx (v + du) (1 - vdu/c^2) . \quad (2.8)$$

Expanding and keeping terms linear in du , we find

$$v + dv = v + du (1 - v^2/c^2) ,$$

or

$$dv = ad\tau (1 - v^2/c^2) . \quad (2.9)$$

This is a differential equation, that can be solved by separation of variables:

$$a\tau = \int_0^v dv' (1 - v'^2/c^2)^{-1} = \frac{c}{2} \log \left(\frac{1 + v/c}{1 - v/c} \right) \quad (2.10)$$

or

$$v(\tau) = c \tanh(a\tau/c) . \quad (2.11)$$

That is, as a function of ship time (*i.e.*, "proper" time), the velocity with respect to S increases from 0, but remains less than c . Its asymptotic value is c .

We would like now to relate the time t in S to the ship's time τ , so we can re-express the speed v as a function of t . Recall that

$$dt = \frac{d\tau}{\sqrt{1 - v^2/c^2}} ,$$

so that

$$t = \int_0^\tau d\tau' \cosh(a\tau'/c) = \frac{c}{a} \sinh(a\tau/c) . \quad (2.12)$$

Therefore

$$v(t) = \frac{at}{\sqrt{1 + (at/c)^2}} . \quad (2.13)$$

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Physical meaning of s^2

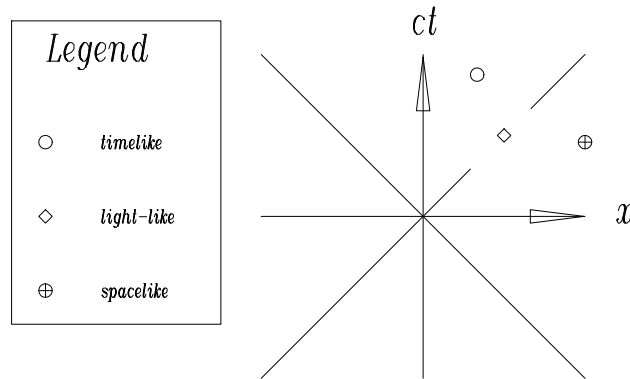
For small times, the speed is given by Newton's formula

$$v = at ;$$

but as time increases without limit, $v \rightarrow c$.

Physical meaning of s^2

The quantity s^2 defined previously is called the *invariant interval* between the origin in Σ and the spacetime event at \mathbf{x} . That is, if we think of the coinciding of the origins of S and S' systems as a space-time event (event $\mathbf{0}$ in S), then the invariant interval represents something about the difference between the point \mathbf{x} and the point $\mathbf{0}$.



The 45° lines represent the light cone, $x=ct$. The points represent events at timelike, lightlike or spacelike intervals from the origin

The physical interpretation is this:

- if $s^2 < 0$, then the interval is called *timelike*, and a light signal can connect the two events $\mathbf{0}$ and \mathbf{x} .
- if $s^2 = 0$, the interval is called *lightlike*.
- if $s^2 > 0$, the interval is called *spacelike* and the events $\mathbf{0}$ and \mathbf{x} cannot be connected by a light signal.

What is this business about light signals? Basically it means that if something takes place at point \vec{x}_A and time t_A , and something else takes place at \vec{x}_B and a later time t_B , if someone could have sent a signal (by light beam, *e.g.*) from \vec{x}_A at time t_A to point \vec{x}_B and the signal could in principle have arrived *before* time t_B , then the event at \vec{x}_A could have caused the event at \vec{x}_B . A simple calculation will show that in that case,

$$s_{AB}^2 = (\vec{x}_A - \vec{x}_B)^2 - c^2(t_A - t_B)^2 < 0.$$

Conversely, if the events are too far apart for a light signal to get from one to the other in time $\delta t = t_B - t_A$, then A could not possibly have caused B . In this case, $s_{AB}^2 > 0$. This is rather fortunate, because if $s_{AB}^2 > 0$, it would be possible for an observer—say in S —to think B occurred *after* A ; while another observer—in S' , say—could determine that B occurred *before* A !